

*VVMethoden – TP2*

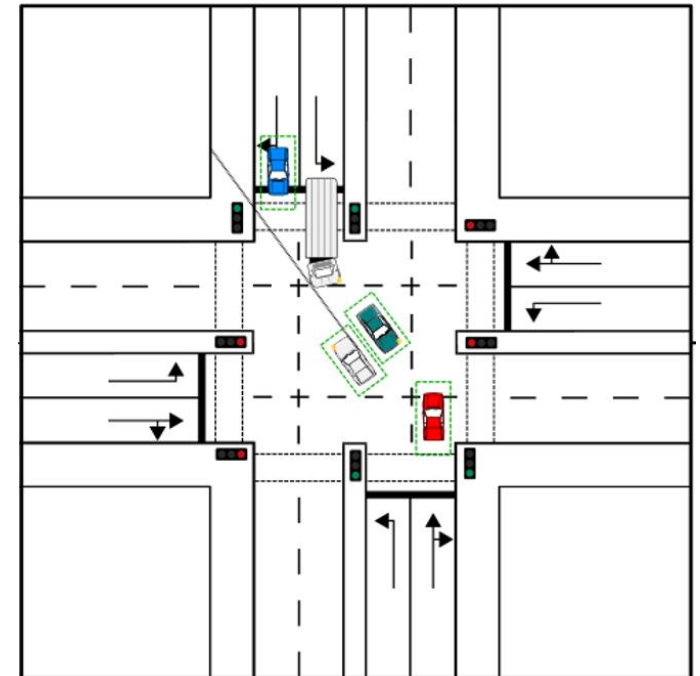
# Criticality Analysis for the Verification and Validation of Automated Vehicles

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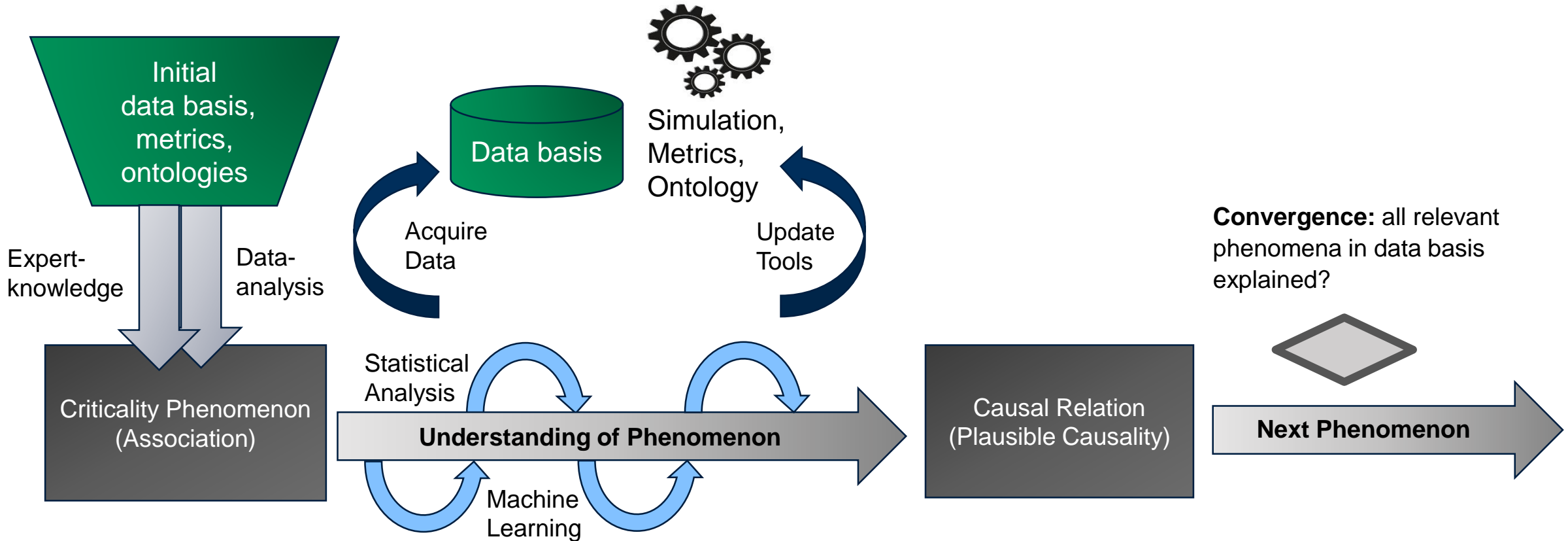
**Goal:** develop a **deep understanding** for the structure of the open context with respect to the emergence of criticality and its conditions.

- Identification and modelling of relevant influencing factors associated with criticality → **criticality phenomena**
- Improved understanding of criticality phenomena by analysis of **causal relations**
- Abstraction leads to classification of scenarios and **condensation of test space**
- **Employed tools:**
  - Metrics, ontologies, simulation
  - Acquisition & management of knowledge and data
  - Statistical analysis, machine learning



Use Case „Urban Intersection“

# Criticality Analysis – Basic Concept



**Assumptions:** Humans are able to drive reasonably safe by recognizing a limited and manageable set of abstract classes of danger, i.e. criticality phenomena → **Finiteness**

The relevant phenomena leave traces in a continuously growing data basis → **Convergence**

# Criticality Phenomenon „Occlusion“

- Identify the criticality phenomenon ‚Occlusion‘ (e.g. via expert knowledge)
  - Find adequate level of abstraction plus relevant concretizations
  - Use ontological representation and classification to organize knowledge

Absolute Cases	Relative Cases	Criticality Phenomenon	Ontological Classification	Estimated Criticality	Tags
2701	21.79%	Occlusion	Perception	Medium	Limited Perception
573	4.62%	Occluded Pedestrian	Perception	High	Limited Perception, VRU
1031	8.32%	Occluded Bicyclist	Perception	High	Limited Perception, VRU
982	7.92%	Occluded Intersecting Vehicle	Perception	Medium	Limited Perception, Trajectory
0	0%	Occluded Obstacle	Perception	Medium	Limited Perception, Obstacle
n.i.	n.i.	Occluded Lane Markings	Perception	High	Limited Perception, Lane Markings
221	1.78%	Occluded Traffic Sign	Perception	Depends	Limited Perception, Traffic Sign
n.i.	n.i.	Occluded Traffic Light	Perception	High	Limited Perception, Traffic Light

- Check available data basis for empirical evidence whether the phenomena are relevant
  - Searching the GIDAS database yields
    - $N = 12394$  accidents in urban areas involving a passenger car
    - $2701 \approx 21,79\%$  are associated with „Occlusion“
  - Strong indication that Occlusion is a relevant phenomenon (even for automated vehicles)

# Causal Relation „Static occlusion of traffic participant“

- Use directed acyclic graphs to represent **hypotheses about the underlying causal relation**
- Incorporate **criticality metrics** as to make criticality measurable, e.g. Time-To-Collision, required acceleration, ...
- Collect evidences for causal relations using **real-world data** and **simulation**
- Use **abstraction/refinement** to find an adequate level of abstraction

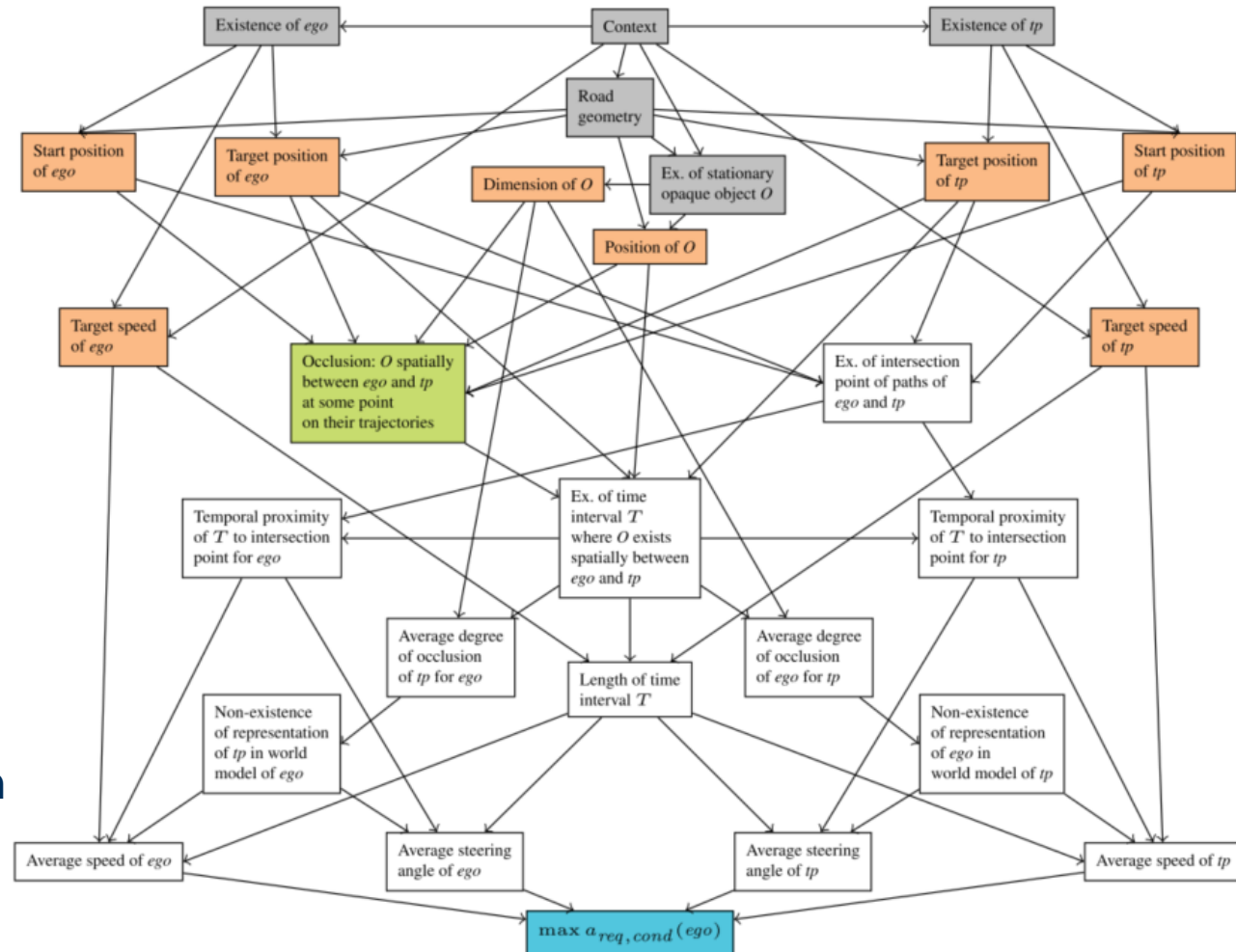
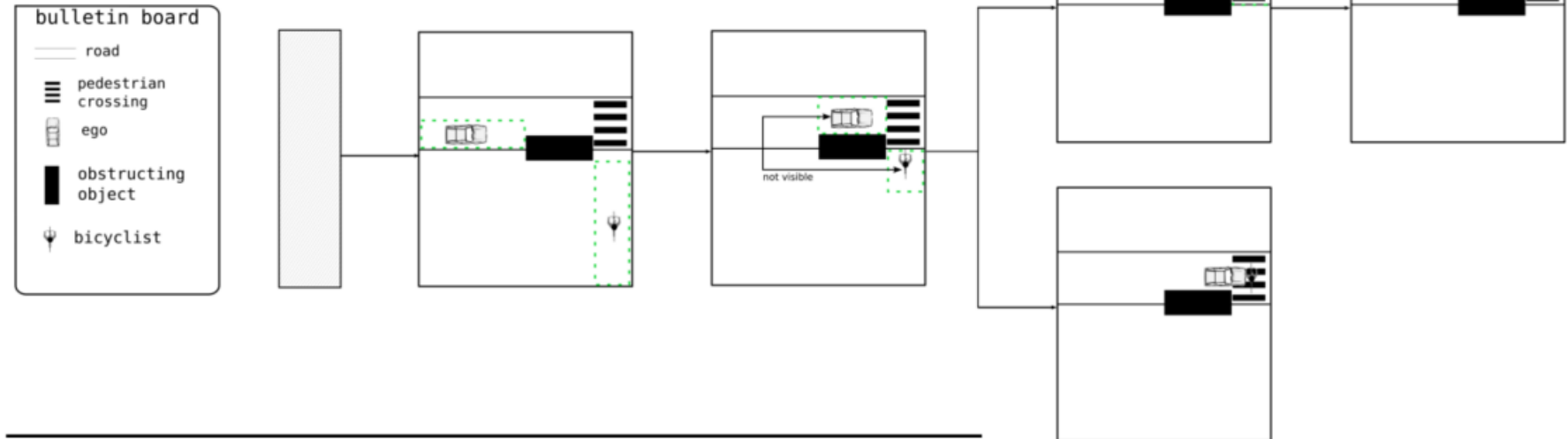


FIGURE 6: Causal relation  $CR_{stat-occ-tp}$ , represented as a DAG, connecting the criticality phenomenon  $CP_{stat-occ-tp}$  to criticality measured via conditional required acceleration ( $a_{req,cond}$ ). Unobserved variables are gray and independent variables are orange. The exposure variable 'occlusion' is marked green. The outcome variable ' $\max a_{req,cond}(ego)$ ' is marked blue.

# Plausibilization of Causal Relations using Simulation

- In order to generate evidences for the causal relation „static occlusion“ consider an **abstract scenario** with a static occlusion present (based on VVM Use Case 2-3)



- For realization in simulation (e.g. OpenPASS, CARLA, ...) derive an associated **logical scenario**

Parameter	Range
<i>ego</i> start position $(x, y)$	$[-58, -33] \times [-29, -28]$
<i>ego</i> target position $(x, y)$	$[50, 55] \times [-29, -28]$
<i>ego</i> target speed $(km/h)$	$[25, 60]$
<i>bicyclist</i> start position $(x, y)$	$[31, 32] \times [3, 15]$
<i>bicyclist</i> target position $(x, y)$	$[-50, -45] \times [-34, -33]$
<i>bicyclist</i> target speed $(km/h)$	$[10, 25]$
Dimension of $O$ (discretized as number of parking cars)	$\{0, 1, 2, 3, 4, 5, 6, 7\}$
Position of $O$ $(x, y)$	$[2, 20] \times ([-35, -34] \cup [-26, -25])$



# Evaluation of Criticality Metrics and Data Analysis

- As to generate data, use **stochastic variation** of parameters (e.g.  $p = 13$ ) to obtain **concrete scenarios** (e.g.  $n = 1000$ ) for simulation and evaluate suitable criticality metrics (e.g.  $m = 2$ )

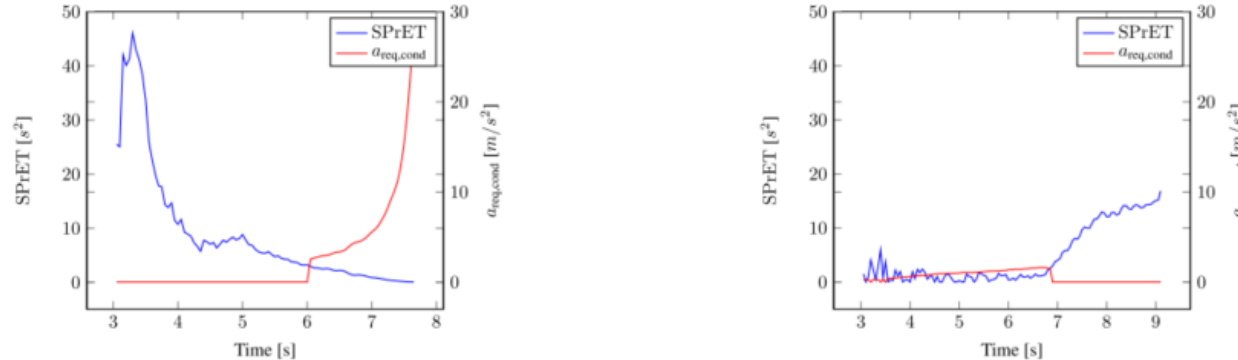
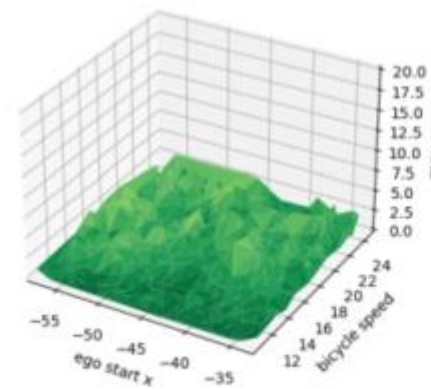


FIGURE 11: SPPrET and  $a_{req,cond}$  over time for a critical occlusion (left) and an uncritical non-occlusion (right) scenario.

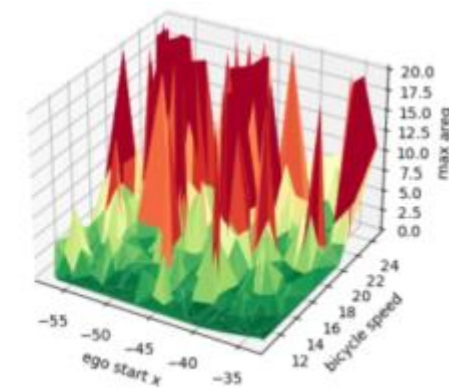
TABLE 2: Significant ( $\alpha = 10^{-9}$ ) results of correlation analysis between variables and  $a_{req,cond}(ego)$  using Spearman's  $\rho$ .

Variable	Correlation ( $\rho$ )	p-value
Occlusion	0.29	$p < 10^{-20}$
Duration of occlusion	0.26	$p < 10^{-15}$
<i>ego</i> starting position ( $x$ )	-0.24	$p < 10^{-14}$
<i>bicyclist</i> starting position ( $y$ )	-0.35	$p < 10^{-29}$
<i>bicyclist</i> target speed	0.42	$p < 10^{-44}$
Position of $O$ ( $y$ )	0.20	$p < 10^{-9}$

- For each simulation run evaluate whether the phenomenon was present (did an occlusion happen or not?)
- Perform statistical analysis of the resulting data set in  $\mathbb{R}^{n \times (m+p)}$



Group A: no occlusion present



Group B: occlusion present

## Further reading

- ▶ Journal Publication „Criticality Analysis for the Verification and Validation of Automated Vehicles“ published at IEEE Access (21.01.2021)
  - ▶ Joint publication by several VVM partners
  - ▶ Authors: Christian Neurohr (OFFIS), Lukas Westhofen (OFFIS), Martin Butz (Bosch), Martin Bollmann (ZF), Ulrich Eberle (Opel), Roland Galbas (Bosch)
  - ▶ [ResearchGate](#)
  - ▶ [IEEEExplore](#)



**Thank you for the attention.**

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# Criticality Analysis – In a Nutshell



Criticality Analysis

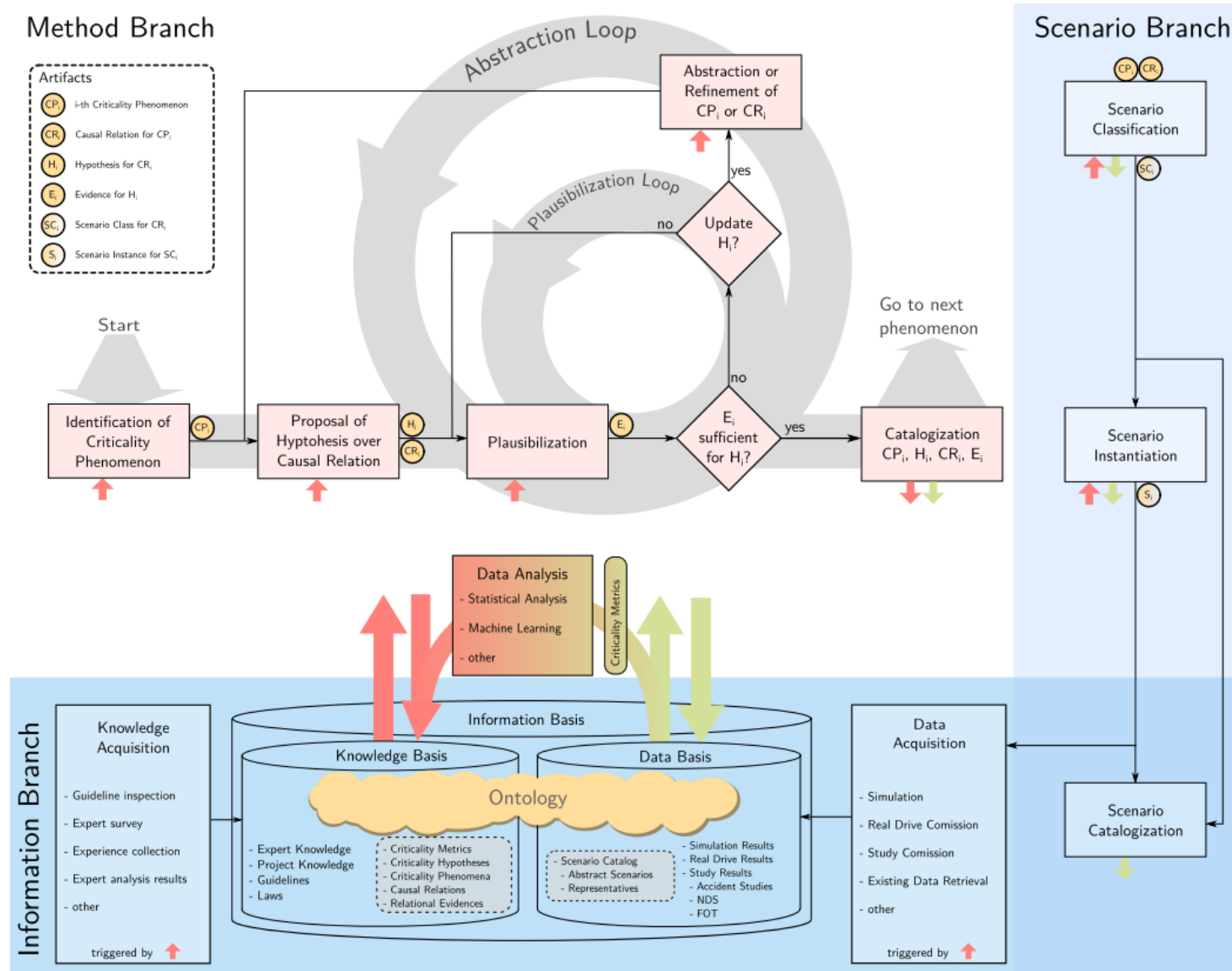
$$\left\{ \infty \mapsto \mathbf{n} \right\}$$

- Criticality Phenomena
- Causal Relations
- Abstract Scenario Catalog

- How can we find all the **relevant artifacts** for the **safe operation** of fully **automated vehicles** within an infinite-dimensional space?

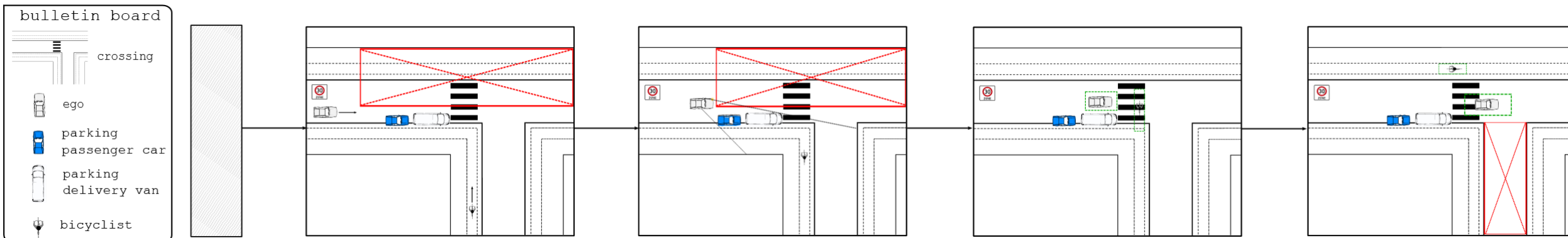
- Extract associations → phenomena
- Find plausible explanations → causality
- Use abstraction → catalogization

# Criticality Analysis – Detailed Flowchart



- **Method Branch** – Identification of criticality phenomena, proposal of causal relations, evidence for plausibility of hypotheses.
- **Information Branch** – Knowledge and data management for the criticality analysis, Ontologies.
- **Scenario Branch** – Scenarios as the 'substrate' of the criticality analysis, a means for structuring processes and description of reality

# Criticality Analysis – Abstract Scenarios



Abstract Scenario: „Occluded Bicyclist at T-intersection“

- Evaluate criticality metrics on scenarios with (and without) phenomena (e.g. occlusion) in order to collect evidences for causal relations
  - Set up simulative experiments using the framework of statistical hypothesis testing
- Build up catalogue of abstract scenarios and use mechanisms for instantiation to more concrete scenarios
- Derive suitable abstract scenario classes with respect to phenomena and causal relations
  - Employ Zone Graphs for classification