

VERIFICATION  
VALIDATION  
METHODS

Final Event 21 / 22 November 2023

# How the VVM overall methodology supports the safety case

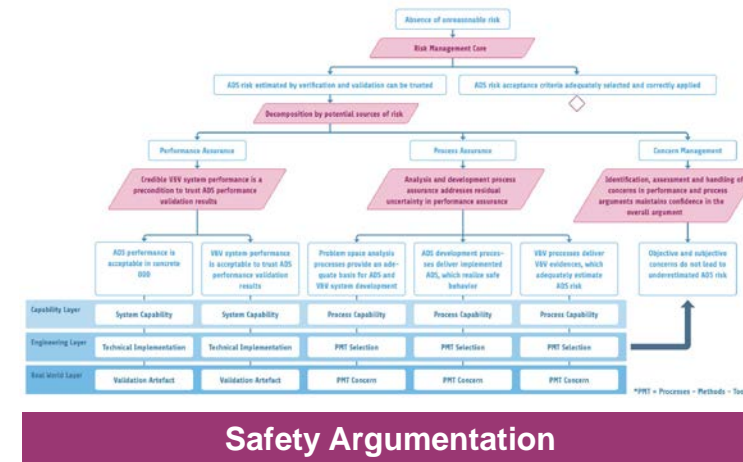
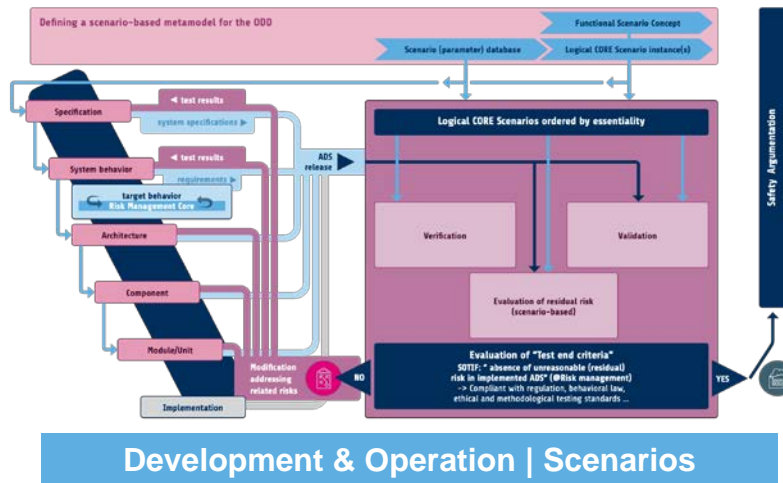
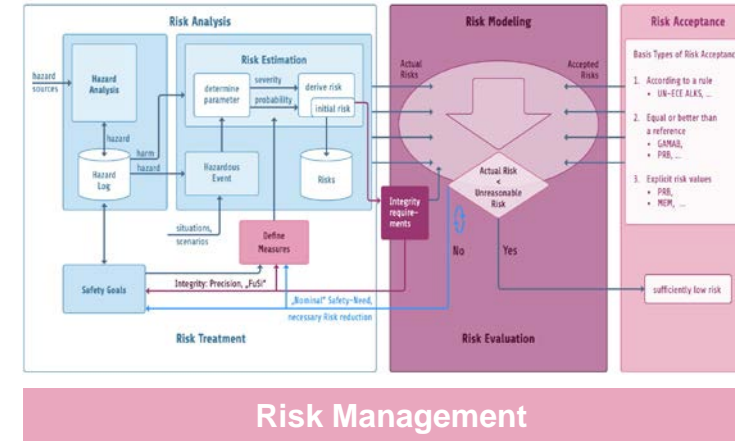
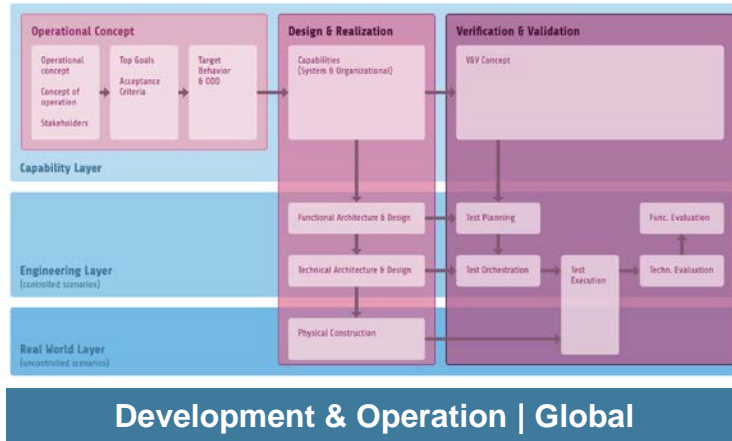
Helmut Schittenhelm, Mercedes-Benz

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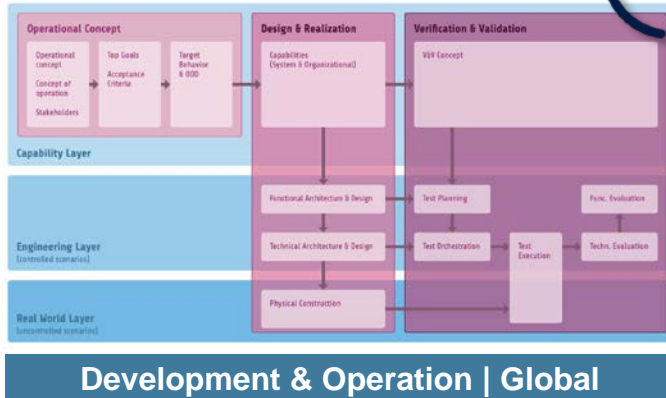
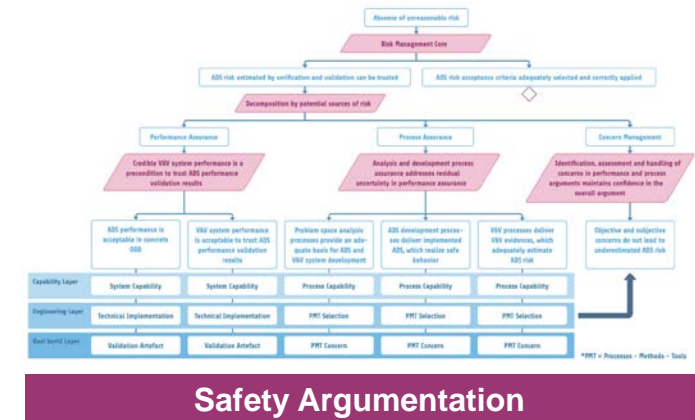
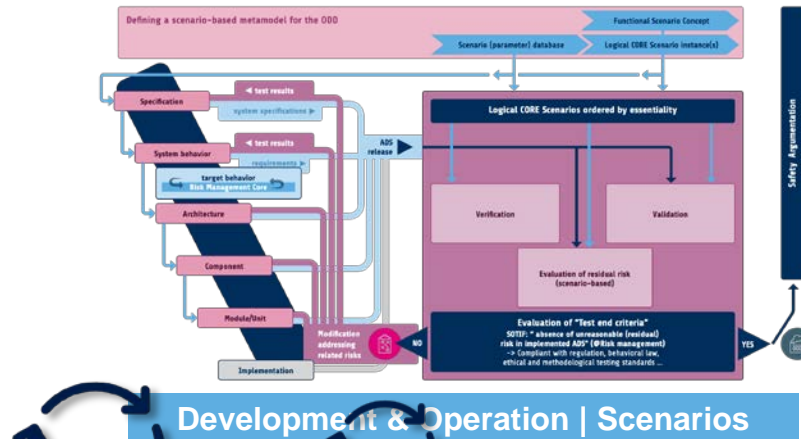


on the basis of a decision  
by the German Bundestag

# The four Elements of the VVM Methodology



# The four Elements of the VVM Methodology



**Overall Methodology – focus: “System Behavior with *acceptable Risk*”**

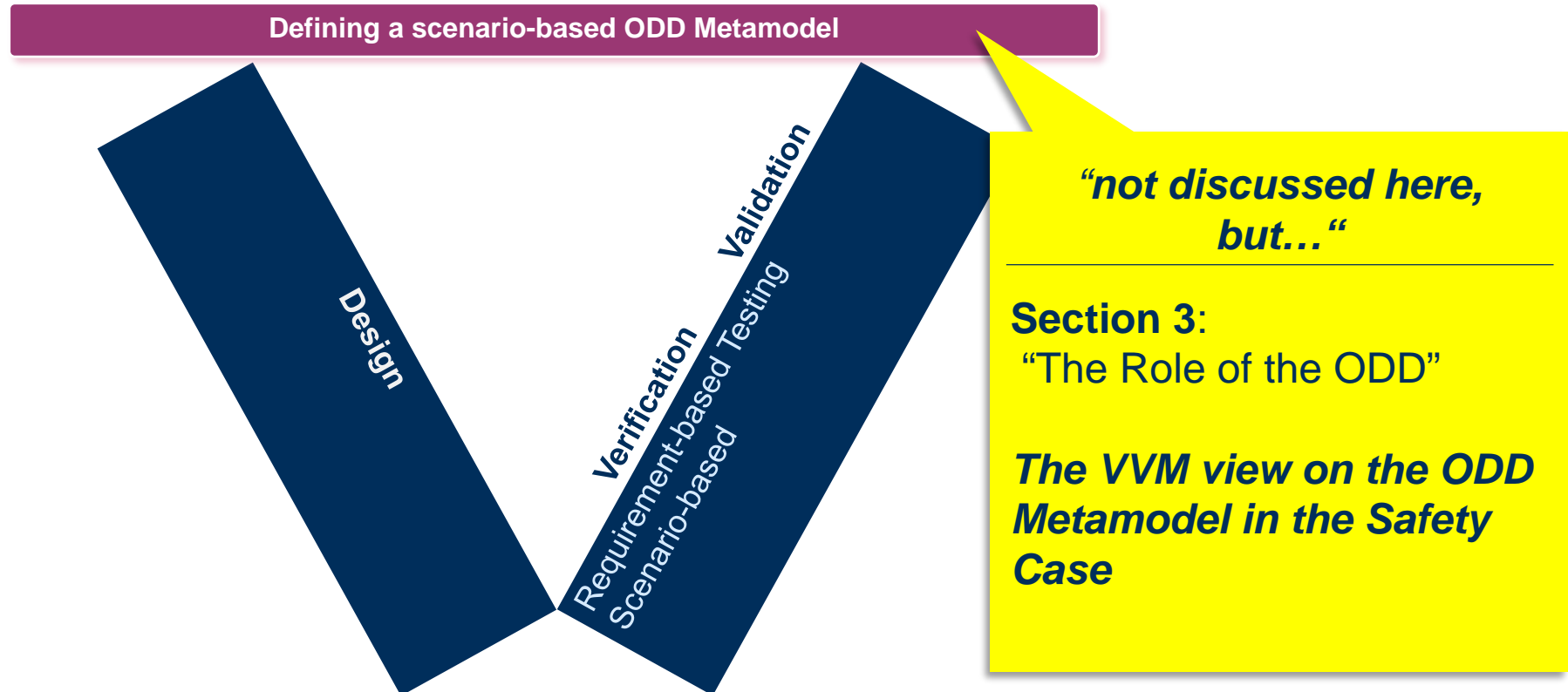


# Overall Methodology

- ▶ Starting with the V-Model ...



- ▶ ... adding an ODD model ...



## ► ... Problem Space Analysis ...

... basis for SOTIF hazard & risk analysis and for definition of safety goals ...

1

Problem Space Analysis

Design

Implementation

Verification  
Requirement-based Test  
Scenario-based Test

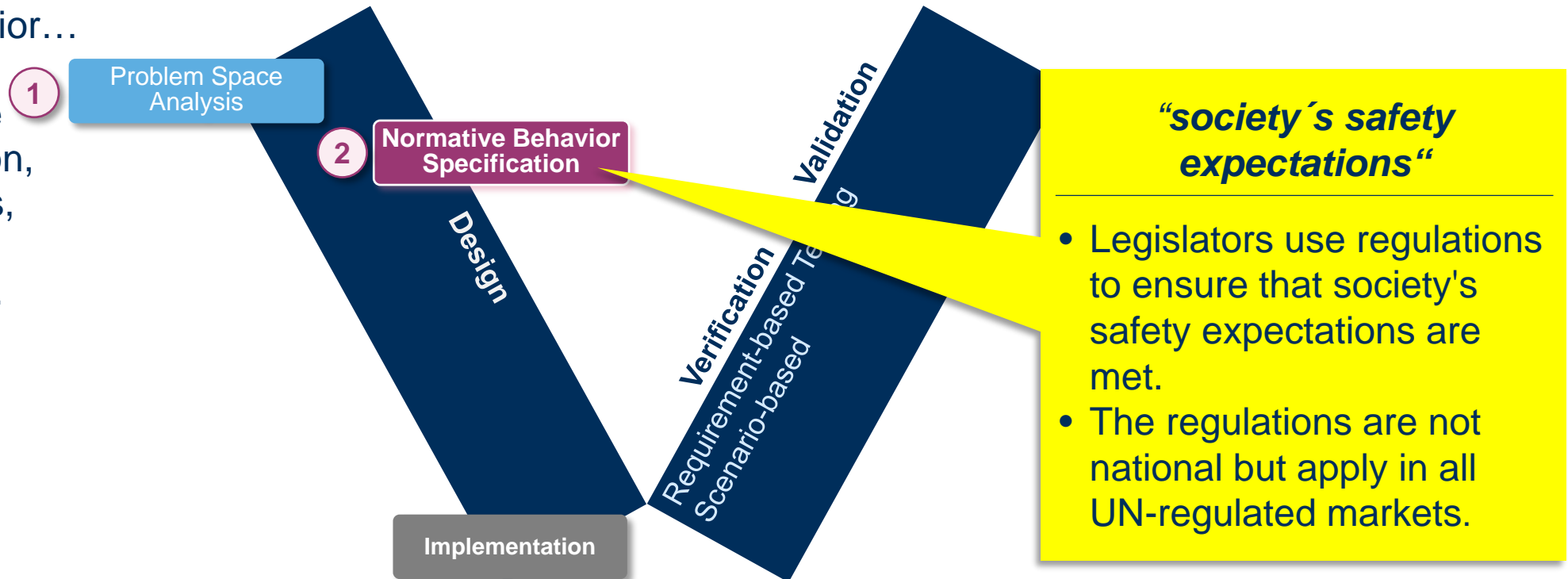
### “Criticality Analysis”

- Accident Database Analysis
- Analysis of existing knowledge and expert know-how
- Analysis of field data
- Simulations
- ...

... a systematic **Analysis of the Problem Space** provides the basis for a **deep understanding of the operational environment** and identifies the **dominant characteristics, risks, relationships and scenario classes** that are **relevant to the safe operation** of an automated driving system...

► ... normative  
System Behavior...

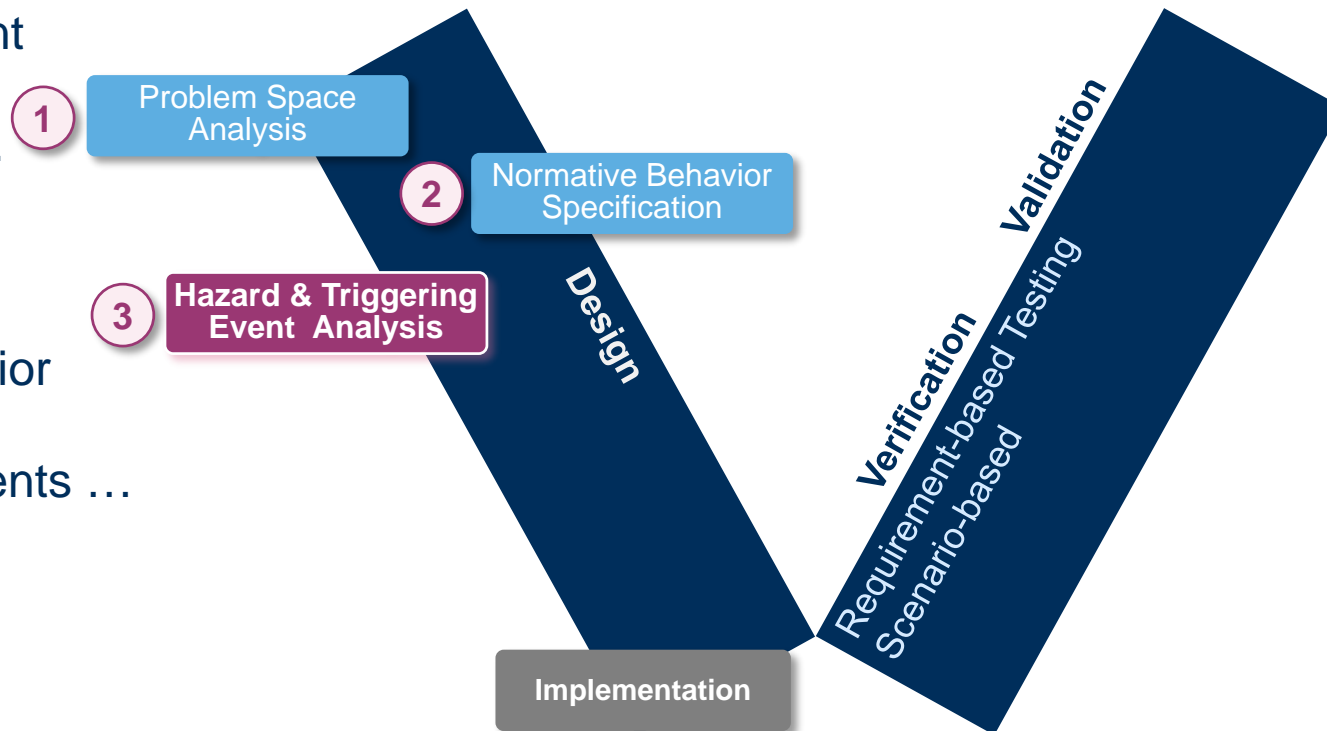
... Compliance  
with certification,  
legal, society's,  
and ethical  
expectations...



... during the specification of the **normative system behavior**, a set of requirements is defined. These requirements represent the legal (e.g. behavioral law), societal, and ethical expectations regarding the automated driving system. Clear definitions of the boundaries of ADS behavior with respect to these constraints are defined ...



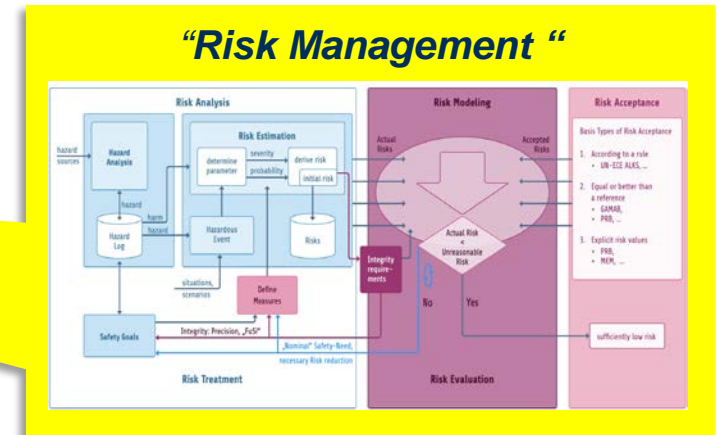
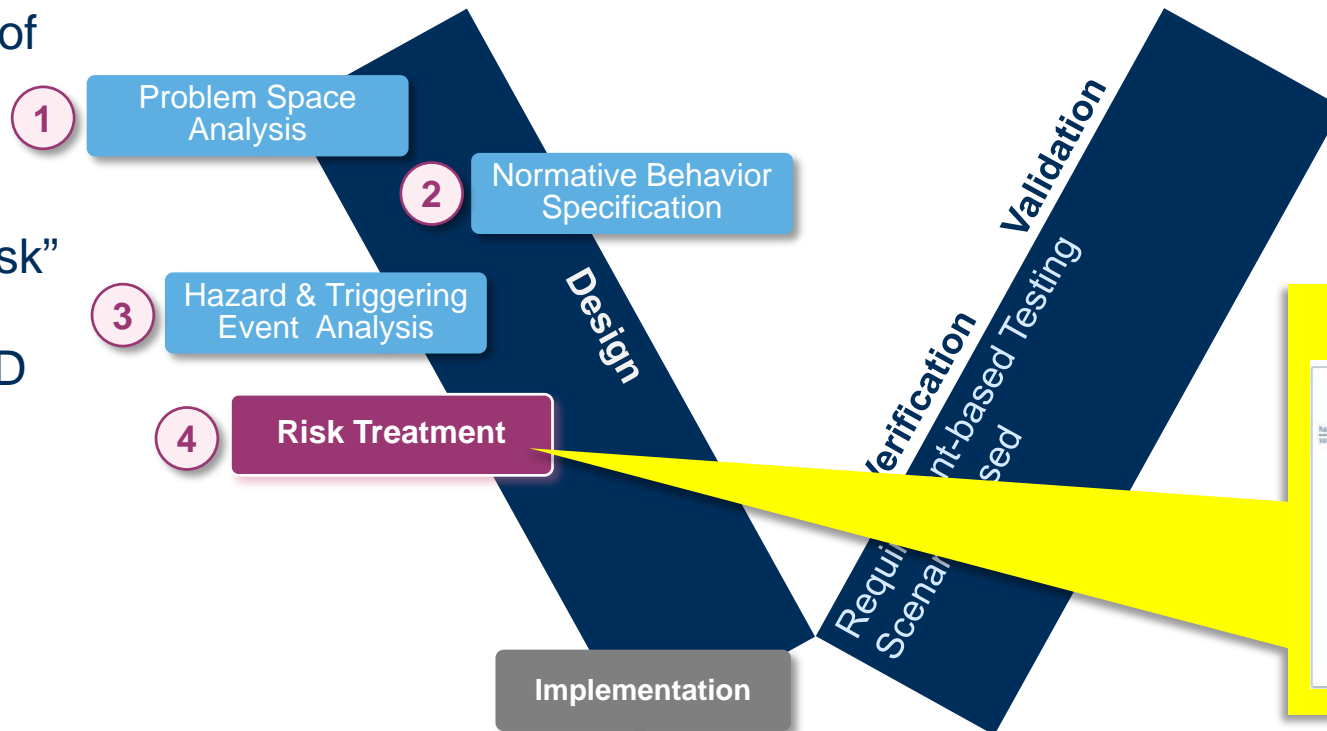
- ▶ ... Hazard and triggering Event Identification and Analysis...
- ... Basis for designing System Behavior to cover all hazardous Events ...



... based on the ODD Metamodel and an understanding of the proposed customer function, a **systematic hazard and risk identification and analysis** is performed for SOTIF. This includes a consideration of a failure in the function together with a systemic view of intrinsically hazardous conditions within the interaction between the ADS equipped vehicle and its environment that need to be avoided....

► ... Management and treatment of Risk ...

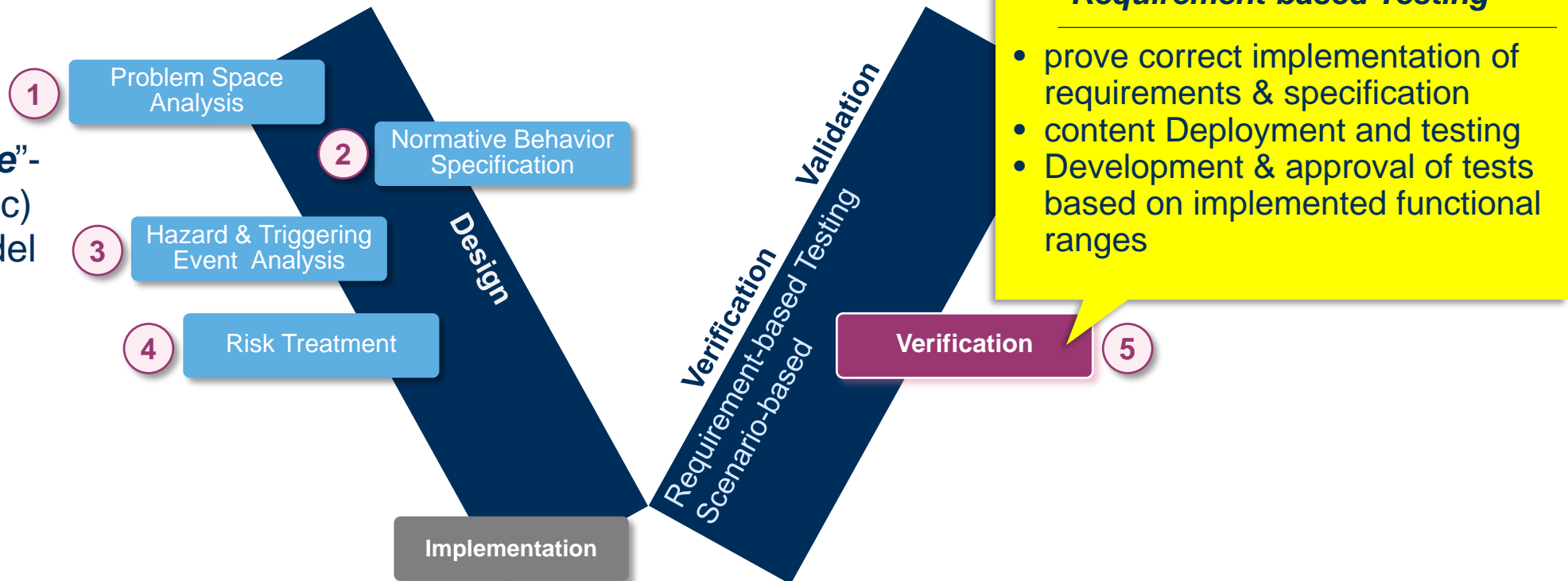
... ensures "acceptable Risk" within System Design for ODD Metamodel...



... In risk management, **safety measures** are defined that result in an **acceptable residual risk** for the automated driving system in hazardous events systemically identified in CORE scenarios and their triggering conditions. For this purpose, the "Risk Management Core" (RMC) is proposed as a process tool. The RMC is an iterative process for aligning actual risk with accepted risk using safety measures. ...

## ► ... Verification...

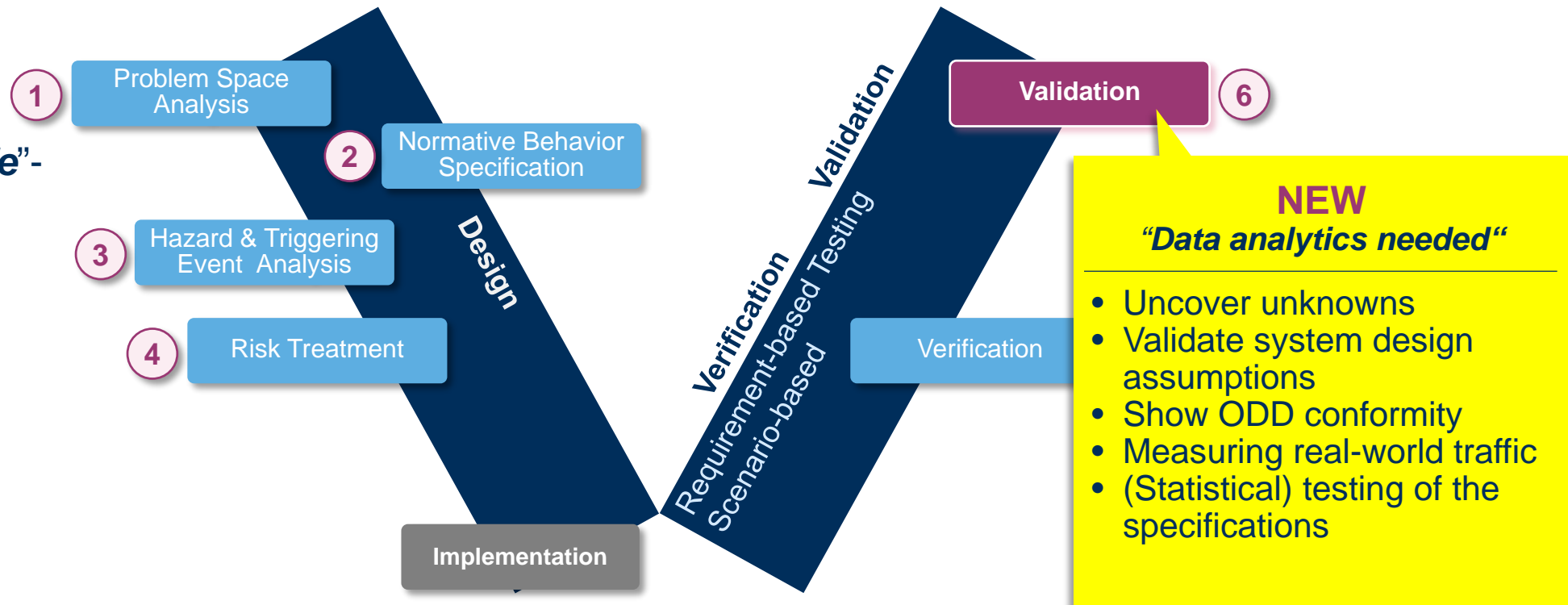
- ... System behaves as specified - "**safe**"- in (deterministic) ODD Metamodel ...



...the **automated driving system** and its components are **verified in order to show that they behave as specified in the ODD Metamodel** especially in known but unsafe (near misses/pot. collisions) regions of all CORE scenarios. Furthermore, it must be proven that the **system** and its **components do not contain any undesired functionality or show operation characteristics which might violate safety objectives** in its ODD...

## ► ... Validation...

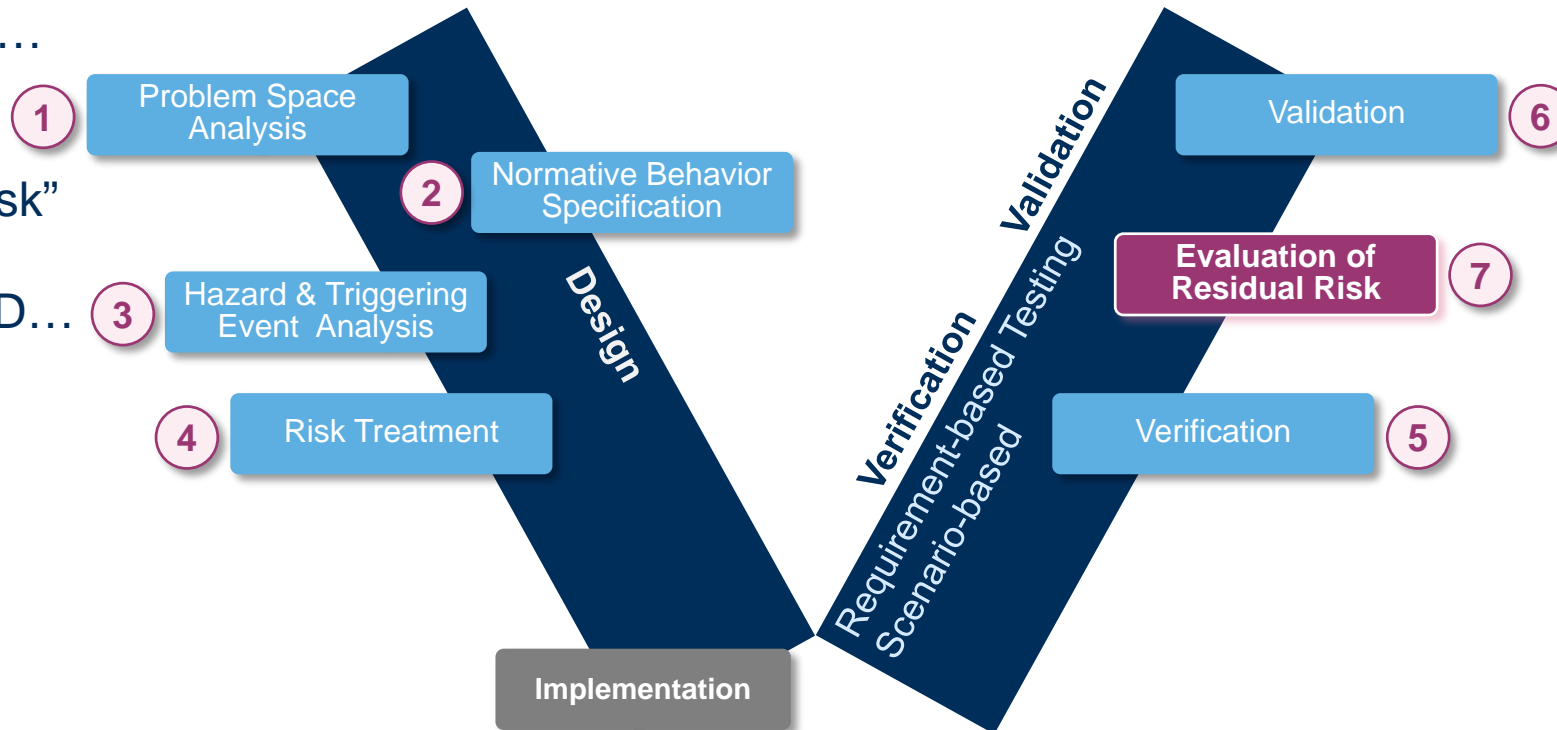
► ... System behaves as specified - “**safe**”- in (stochastic) ODD ...



... validation proves “Is the specification correct and sufficient?” respectively “Are Stakeholder especially customer approvals available?”. Beyond safety and law compliant behavior, Usability, Controllability and acceptability are validation objectives. Validation includes the validation of the ODD Metamodell ...

► ... Evaluation of Residual Risk ...

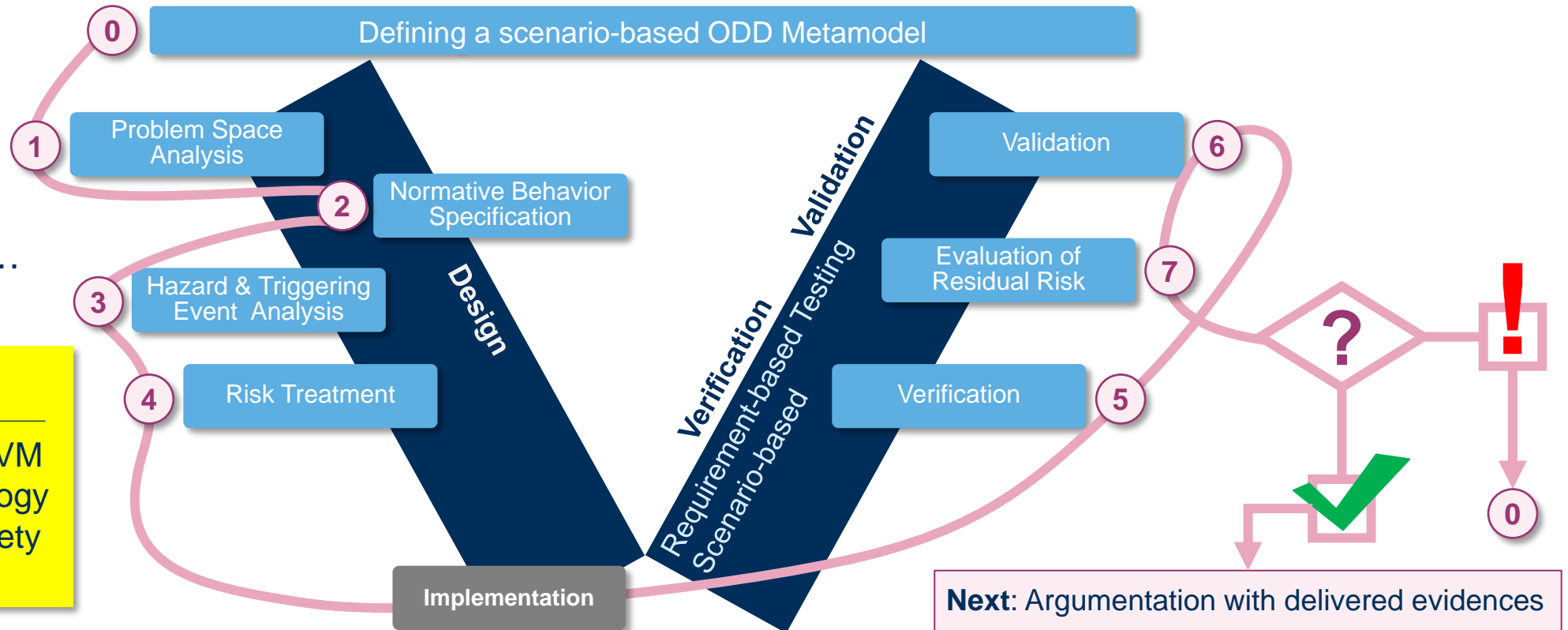
... validates “acceptable Risk” within System Design for ODD...



... Evaluation of potential safety risks & compliance with legal requirements consists of three components, the simulation to verify the functional correctness and safe behavior of the driving function in the ODD Metamodel, the evaluation of the sensor performance in real traffic, and an assessment regarding acceptable residual risk and legal compliance. ...

► VVM overall Approach argues with evidences provided by this structure ...

**“Resume”**  
How does the VVM overall methodology supports the safety case?



... For each method selected to provide confirmation of a particular quality attribute in the VVM overall approach, a set of criteria has been defined that assesses the contribution of the analysis, verification or test method to the associated quality attribute as directly as possible. The achievement of these criteria is then the "reason" for the corresponding statements in the safety case...

# Thank you!

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A project developed by the VDA Leitinitiative  
autonomous and connected driving

Supported by:



on the basis of a decision  
by the German Bundestag